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## The Fundamental Solution for Second Order Elliptic Differential Equations

## 1. Introduction

Let  $D$  be a bounded domain in the Euclidean  $m$ -space  $R^m$  ( $m \geq 3$ ). We shall denote its boundary by  $\partial D$  and its closure by  $\bar{D}$ . If  $\Omega$  is a bounded set such that  $\bar{\Omega} \subset D$ , we shall write  $\Omega \Subset D$ . Let the partial differential operator  $L$  defined by

$$Lu = \sum_{i,j=1}^m a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^m b_i(x) \frac{\partial u}{\partial x_i} + c(x)u$$

be elliptic in  $D$ . Denote by  $\tilde{D}$  the set  $\tilde{D} = (\bar{D} \times \bar{D}) \setminus (\partial D \times \partial D)$ .

Definition 1 (cf. [5]). A function  $G = G_D(x, y)$  will be called a *Green function* for the equation  $Lu = 0$  with respect to the domain  $D$  if

- 1°  $G_D(x, y)$  is continuous on  $\tilde{D}$ , for  $x \neq y$ ,
- 2°  $G_D(x, y) = 0$  for  $x \in \partial D$ ,  $y \in D$ ,
- 3° the integral

$$I_G(x) = \int_D G_D(x, y) f(y) dy$$

is of class  $C^2$  on  $D$ , continuous on  $\bar{D}$  and satisfies the identity

$$L[I_G(x)] = -f(x)$$

for all  $f(x)$  in  $C_0^{(\lambda)}(D)$  — class of Hölder-continuous functions (with exponent  $\lambda$ ) with compact support in  $D$ .

Definition 2. A domain  $D$  having the property that the Green function  $G_D(x, y)$  there exists is termed a *regular domain*.

Let  $D_0 \subset R^m$  be a bounded or unbounded domain. In particular, it may happen that  $D_0 = R^m$ . Suppose that there exists a sequence  $D_1, D_2, \dots$  of

bounded and regular domains satisfying the following properties:  $D_n \subset D_{n+1}$ ,  $D_n \Subset D_0$ ,  $D_n \rightarrow D_0$ . Let  $G_n(x, y)$  be the Green function for the equation  $Lu = 0$  with respect to the domain  $D_n$ .

The main purpose of this paper is to show that the sequence  $\{G_n(x, y)\}$  converges. The limit function will be called a *fundamental solution* for the equation  $Lu = 0$  with respect to the domain  $D_0$ . Another purpose of our consideration is to obtain some estimation for the fundamental solution. This estimation is of particular interest if  $D_0$  is unbounded, for example if  $D_0 = R^m$ .

## 2. Some properties of the Green function

Suppose that the coefficients of the operator  $L$  satisfy assumptions of Hopf theorem (see [3]). Under the above conditions we have

**Lemma 1** ([5]). *There is at most one Green function with respect to the domain  $D$  and the inequality  $G_D(x, y) \geq 0$  holds for any two points  $x, y$  in  $D$ ,  $x \neq y$ , provided  $G_D(x, y)$  exists.*

**Lemma 2** ([5]). *If  $D \subset D_1$ , then  $G_D(x, y) \leq G_{D_1}(x, y)$  for  $(x, y) \in \tilde{D}$ ,  $x \neq y$ , provided  $G_D(x, y)$  and  $G_{D_1}(x, y)$  exist.*

**Definition 3.** We denote by  $A(L, D_0)$  the family of all functions  $h(x, y; \alpha)$  continuous for  $(x, y) \in \{(x, y) : x \in D_0, y \in D_0, x \neq y\}$  which are twice continuously differentiable with respect to the first argument  $x \in D_0$ ,  $x \neq y$ , and such that the following properties are satisfied:

- 1°  $h(x, y; \alpha) = 0(r^{-m+2+\alpha})$  as  $r \rightarrow 0$ , where  $r = |x - y|$ ,  $0 < \alpha < 1$ ,
- 2°  $\frac{\partial}{\partial x_i} h(x, y; \alpha) = 0(r^{-m+1+\alpha})$ ,  $\frac{\partial^2}{\partial x_i \partial x_j} h(x, y; \alpha) = 0(r^{-m+\alpha})$ , as  $r \rightarrow 0$ ,
- 3°  $L_x h(x, y; \alpha)$  is continuous with respect to  $(x, y) \in D_0 \times D_0$ ,  $x \neq y$  and  $L_x h(x, y; \alpha) < 0$  for  $x, y \in D_0$ ,  $x \neq y$ ,
- 4°  $h(x, y; \alpha) > 0$  for  $x, y \in D_0$ ,  $x \neq y$ .

The symbol  $L_x$  denotes the operator  $L$  applied with respect to the variables  $x$ . This notation will be of importance later when we shall be dealing with functions of  $x$  and  $y$ , both in  $R^m$ . Under the hypotheses of theorem 3 of [5] the function  $r^{-m+2+\alpha} \in A(L, D_0)$ . Let  $\varrho_\varepsilon(t)$  be a  $C^\infty[(0, \infty)]$  function such that

$$\varrho_\varepsilon(t) = \begin{cases} 1 & \text{for } 0 \leq t \leq \frac{\varepsilon}{2}, \\ 0 & \text{for } t > \varepsilon. \end{cases}$$

**Theorem 1.** *Let  $D$  be a regular domain. Assume that the operator  $L$  is elliptic in  $D_0 \supset D$ , the coefficients of  $L$  are Hölder continuous on  $D_0$  with exponent  $\lambda$  ( $0 < \lambda < 1$ ),  $c(x) \leq 0$  on  $D_0$  and there exists the function  $h(x, y; \alpha) \in A(L, D_0)$ , where  $\alpha < \lambda$ . Then for every point  $y_0 \in D$  and for any number  $\varepsilon > 0$  such that  $K(y_0, 2\varepsilon) = \{y : |y - y_0| \leq 2\varepsilon\} \Subset D$ , there exists a constant  $M > 0$  such that*

$$G_D(x, y) \leq U_\varepsilon(x, y) + Mh(x, y; \alpha)$$

for  $x \in \bar{D}$ ,  $y \in K(y_0, \varepsilon)$ , where

$$U_\varepsilon(x, y) = (m-2)^{-1} \omega_m^{-1} [A(y)]^{-\frac{1}{2}} \left[ \sum_{i,j=1}^m A_{ij}(y) (x_i - y_i)(x_j - y_j) \right]^{\frac{-m+2}{2}} \varrho_\varepsilon(|x-y|),$$

$[A_{ij}(y)]$  is the inverse matrix to  $[a_{ij}(y)]$ ,  $\omega_m$  is the area of the unit sphere in  $R^m$  and  $A(y)$  is the determinant of the matrix  $[A_{ij}(y)]$ . Constant  $M$  may be chosen independently of  $D$ .

Proof. Let  $y_0$  be a fixed point in  $D$  and  $\varepsilon$  a positive number such that  $K(y_0, 2\varepsilon) \subset D$ . Consider the function

$$\Phi(x, y) = -U_\varepsilon(x, y) - Mh(x, y; \alpha) + G_D(x, y).$$

The constant  $M$  will be defined later. Let  $I_\Phi(x)$  denote the integral

$$(1) \quad I_\Phi(x) = \int_D \Phi(x, y) f(y) dy,$$

where  $f(y) \in C_0^{(0+\lambda)}(D)$ . Then

$$I_\Phi(x) = - \int_D U_\varepsilon(x, y) f(y) dy - M \int_D h(x, y; \alpha) f(y) dy + \int_D G_D(x, y) f(y) dy.$$

These integrals are in class  $C^2(D)$  (see [3]). Hence

$$(2) \quad L[I_\Phi(x)] = L \left[ - \int_D U_\varepsilon(x, y) f(y) dy \right] - ML \left[ \int_D h(x, y; \alpha) f(y) dy \right] + L \left[ \int_D G_D(x, y) f(y) dy \right].$$

$U_\varepsilon(x, y)$  is the Levi's function (see [3]). This together with the Poisson's theorem (see [3]) show that

$$(3) \quad L \left[ - \int_D U_\varepsilon(x, y) f(y) dy \right] = f(x) - \int_D L_x [U_\varepsilon(x, y)] f(y) dy.$$

Now we have

$$(4) \quad L \left[ \int_D h(x, y; \alpha) f(y) dy \right] = \int_D L_x [h(x, y; \alpha)] f(y) dy$$

(for details see [3]). From (2), (3), (4) and the definition of Green's function we obtain

$$L[I_\Phi(x)] = - \int_D L_x [U_\varepsilon(x, y)] f(y) dy - M \int_D L_x [h(x, y; \alpha)] f(y) dy$$

or

$$L[I_\Phi(x)] = \int_D L_x [-U_\varepsilon(x, y) - Mh(x, y; \alpha)] f(y) dy.$$

On the other hand,

$$L_x [U_\varepsilon(x, y)] = 0(r^{-m+\lambda}) \quad \text{and} \quad L_x [h(x, y; \alpha)] = 0(r^{-m+\alpha}).$$

