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On a Difference Method for Non-linear Parabolic Equations with Mixed Derivatives

1. In this paper we present a difference method for the non-linear parabolic equation with mixed derivatives

$$(1.1) \quad \frac{\partial u}{\partial t} = f\left(t, x, u, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial x^2}, \frac{\partial^2 u}{\partial x \partial x}\right),$$

where $x = (x_1, \dots, x_p)$, $u = u(t, x)$,

$$\frac{\partial u}{\partial x} = \left(\frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_p}\right), \quad \frac{\partial^2 u}{\partial x^2} = \left(\frac{\partial^2 u}{\partial x_1^2}, \dots, \frac{\partial^2 u}{\partial x_p^2}\right),$$

$$\frac{\partial^2 u}{\partial x \partial x} = \left(\frac{\partial^2 u}{\partial x_1 \partial x_2}, \dots, \frac{\partial^2 u}{\partial x_1 \partial x_p}, \frac{\partial^2 u}{\partial x_2 \partial x_3}, \dots, \frac{\partial^2 u}{\partial x_{p-1} \partial x_p}\right)$$

with initial and boundary conditions

$$(1.2) \quad \begin{cases} u(0, x) = \varphi(x) \\ \frac{\partial u}{\partial x_j} = \varphi_j(t, x'_j) \quad \text{for } x_j = 0, \quad j = 1, \dots, p, \\ \frac{\partial u}{\partial x_j} = \psi_j(t, x''_j) \quad \text{for } x_j = a, \quad j = 1, \dots, p, \end{cases}$$

where $x'_j = (x_1, \dots, x_{j-1}, 0, x_{j+1}, \dots, x_p)$, $x''_j = (x_1, \dots, x_{j-1}, a, x_{j+1}, \dots, x_p)$.

Assuming conditions (1.2) with

$$(1.3) \quad \varphi_j(t, x'_j) = \psi_j(t, x''_j) = 0$$

for a non-linear parabolic equation without mixed derivatives Z. Kowalski [2] solved the problem by proving the convergence of a difference method. On the

other hand for the equation (1.1) and the conditions

$$(1.4) \quad \begin{cases} u(0, x) = \varphi(x) \\ u(t, x'_j) = \varphi_j(t, x'_j) \quad \text{for } x_j = 0, \quad j = 1, \dots, p \\ u(t, x''_j) = \psi_j(t, x''_j) \quad \text{for } x_j = a, \quad j = 1, \dots, p \end{cases}$$

a difference method has been introduced and investigated by A. Fitzke [1].

In the present paper we propose a difference method, similar to that in the paper [1], for solving the equation (1.1) with conditions (1.2). The proof of the convergence is based on our previous results [3] concerning the convergence of various difference methods. An error estimation will also be given.

2. Let us denote

$$(2.1) \quad D_T = \{(t, x): 0 \leq t \leq T, \quad 0 \leq x_j \leq a, \quad j = 1, \dots, p\}$$

In the set D_T we introduce a net with the time-step $k = T/N_1$ and the space-step $h = a/N$, where N_1 and N are positive integers. We denote by $M = (\mu, m)$, where $m = m_1, \dots, m_p$, the nodal point (t^μ, x^m) , with $t^\mu = \mu k$, $x^m = mh$. We shall also use the notation i and j for p -dimensional indices with all coordinates equal to zero except the i -th, resp. the j -th, which equals 1. Here we make the following convention: whenever the i and j are written as upper indices they are to be understood as p -dimensional.

Consider the following two sets Z and Z^+

$$(2.2) \quad Z = \{(\mu, m): 0 \leq \mu \leq N_1, \quad 0 \leq m_j \leq N, \quad j = 1, \dots, p\}$$

$$(2.3) \quad Z^+ = \{(\mu, m): 0 \leq \mu \leq N_1, \quad 0 \leq m_j \leq N, \quad j = 1, \dots, p, \\ \text{except of at most two values } i \text{ and } j \text{ for which } -1 \leq m_i \leq N+1, \\ -1 \leq m_j \leq N+1\}.$$

We introduce the set Z^+ since we shall consider the difference quotients only at the points of the set Z , but in expressions for difference quotients the points of Z^+ may occur.

The values of a function v at the nodal points M we denote by v^M . Following [1] we define the terms:

$$(2.4) \quad \delta v^{M_j} = \frac{v^{\mu m+j} - v^{\mu m-j}}{2h}$$

$$(2.5) \quad \delta v^M = (\delta v^{M_1}, \dots, \delta v^{M_p})$$

$$(2.6) \quad \sigma v^{M_{jj}} = \frac{1}{h^2(p-1)} \sum_{i \neq j} (\alpha(v^{\mu m+i+j} - 2v^{\mu m+i} + v^{\mu m+i-j}) + \\ + \beta(v^{\mu m+j} - 2v^{\mu m} + v^{\mu m-j}) + \alpha(v^{\mu m-i+j} - 2v^{\mu m-i} + v^{\mu m-i-j}))$$

$$(2.7) \quad \sigma v^M = (\sigma v^{M_{11}}, \dots, \sigma v^{M_{pp}})$$

$$(2.8) \quad \varrho v^{M_{ij}} = \frac{1}{4h^2} (v^{\mu m+i+j} + v^{\mu m-i-j} - v^{\mu m+i-j} - v^{\mu m-i+j})$$

$$(2.9) \quad \varrho v^M = (\varrho v^{M_{12}}, \dots, \varrho v^{M_{1p}}, \varrho v^{M_{22}}, \dots, \varrho v^{M_{p-1p}})$$

where i and j on the right-hand sides are the above defined p -dimensional indices and α and β are the positive constants satisfying the condition $2\alpha + \beta = 1$.

3. We denote by E the set

$$E = \{(t, x, u, p, q, w): (t, x) \in D_T, -\infty < u < +\infty, -\infty < p_i < +\infty, \\ -\infty < q_i < +\infty, -\infty < w_{ij} < +\infty, i = 1, \dots, p, j = 1, \dots, p, i < j\}$$

Assumptions A :

- (i) the function $f(t, x, u, p, q, w)$ is of class C^1 in the set E ,
 (ii) there are such positive constants α, β , that $2\alpha + \beta = 1$ and the steps k and h may be so chosen that the inequalities

$$(3.1) \quad \left| \frac{\partial f}{\partial p_i} \right| < \frac{2}{2h} \left(\beta \frac{\partial f}{\partial q_i} - \frac{2\alpha}{p-1} \sum_{j \neq i} \frac{\partial f}{\partial q_j} \right)$$

$$(3.2) \quad \left| \frac{\partial f}{\partial w_{ij}} \right| < \frac{4\alpha}{p-1} \left(\frac{\partial f}{\partial q_i} + \frac{\partial f}{\partial q_j} \right)$$

$$(3.3) \quad 1 + k \frac{\partial f}{\partial u} - \frac{2\beta k}{h^2} \sum_{i=1}^p \frac{\partial f}{\partial q_i} > 0$$

hold in the set E ,

- (iii) the function $u(t, x)$ is of class C^2 in the set D_T and satisfies the equation (1.1) with the conditions (1.2).

4. Now we shall define the values of the solution at the nodal points of $Z^+ \setminus Z$

$$(4.1) \quad \begin{aligned} |u^{\mu m+i} &= u^{\mu m-i} + 2h\varphi_i(t^\mu, x^m) & \text{for } m_i = N \\ u^{\mu m-i} &= u^{\mu m+i} - 2h\varphi_i(t^\mu, x^m) & \text{for } m_i = 0 \\ u^{\mu m+i+j} &= u^{\mu m-i-j} + 2h(\varphi_i(t^\mu, x^m) + \varphi_j(t^\mu, x^m)) & \text{for } m_i = m_j = N \\ u^{\mu m-i-j} &= u^{\mu m+i+j} - 2h(\varphi_i(t^\mu, x^m) + \varphi_j(t^\mu, x^m)) & \text{for } m_i = m_j = 0 \\ u^{\mu m-i+j} &= u^{\mu m+i-j} - 2h(\varphi_i(t^\mu, x^m) - \varphi_j(t^\mu, x^m)) & \text{for } m_i = 0, m_j = N \end{aligned}$$

The u^M just defined satisfies the conditions

$$(4.2) \quad \begin{aligned} u^M &= \varphi(x^m) & \text{for } M = (0, m) \in Z \\ \delta u^{M_j} &= \varphi_j(t^\mu, x^m) & \text{for } m_j = 0, M \in Z, j = 1, \dots, p \\ \delta u^{M_j} &= \varphi_j(t^\mu, x^m) & \text{for } m_j = N, M \in Z, j = 1, \dots, p \end{aligned}$$

The first condition follows from assumptions A , the other two from (4.1).

5. Lemma 1. If the assumptions A are fulfilled, then we have

$$(5.1) \quad \frac{u^{\mu+1m} - u^{\mu m}}{k} = f(t^\mu, x^m, u^M, \delta u^M, \sigma u^M, \rho u^M) + \eta^M$$

$$\text{for } 0 \leq \mu \leq N_1 - 1, 0 \leq m_j \leq N, j = 1, \dots, p,$$

$$(5.2) \quad \lim_{h \rightarrow 0} \max_M |\eta^M| = 0.$$

Proof. Since the function u is of class C^2 in D_T , then (5.1) and (5.2) are satisfied at any inner nodal point M for which $1 \leq m_j \leq N-1$. We shall show that the equation (5.1) is also satisfied for the boundary nodal points. By (4.2) it is clear that $\delta u^{Mj} \rightarrow \frac{\partial u}{\partial x_j}$ as $h \rightarrow 0$, thus it remains to prove that for boundary nodal points we have

$$1^\circ \quad \sigma u^{Mjj} \rightarrow \frac{\partial^2 u}{\partial x_j^2} \quad \text{as } h \rightarrow 0,$$

$$2^\circ \quad \rho u^{Mij} \rightarrow \frac{\partial^2 u}{\partial x_i \partial x_j} \quad \text{as } h \rightarrow 0.$$

Suppose that $m_j^1 = 0$ i.e. the nodal point is on the hyperplane $x_j = 0$. Consider the three groups of indices:

$$I_1 = \{i: (\mu, m+i) \in Z \text{ and } (\mu, m-i) \in Z\}$$

$$I_2 = \{i: |m_i| = 0\}$$

$$I_3 = \{i: m_i = N\}.$$

Using (2.6) and (4.1) we have

$$\begin{aligned} \sigma u^{Mjj} &= \frac{2\alpha}{(p-1)h^2} \sum_{i \in I_1} u^{\mu m+i+j} - u^{\mu m+i} + u^{\mu m-i+j} - u^{\mu m-i} - h(\varphi_j(t^\mu, x^{m+i}) + \varphi_j(t^\mu, x^{m-i})) + \\ &+ \sum_{i \in I_2} 2(u^{\mu m+i+j} - u^{\mu m+i}) + h(\varphi_j(t^\mu, x^m) + \varphi_i(t^\mu, x^m) - \varphi_i(t^\mu, x^{m+j}) - \varphi_j(t^\mu, x^{m+i}) + \\ &+ \sum_{i \in I_3} 2(u^{\mu m-i+j} - u^{\mu m-i}) + h(\psi_i(t^\mu, x^{m+j}) + \varphi_j(t^\mu, x^{m-i}) - \varphi_j(t^\mu, x^m) - \psi_i(t^\mu, x^m)) + \\ &+ \frac{2\beta}{h^2} ((u^{\mu m+j} - u^{\mu m} - h\varphi_j(t^\mu, x^m)). \end{aligned}$$

With the aid of Taylor's expansion at the point (t^μ, x^m) we obtain:

for $i \in I_1$:

$$\begin{aligned} u^{\mu m+i+j} - u^{\mu m+i} + u^{\mu m-i+j} - u^{\mu m-i} - h(\varphi_j(t^\mu, x^{m+i}) + \varphi_j(t^\mu, x^{m-i})) = \\ = h^2 \frac{\partial^2 u}{\partial x_j^2} + 2h \frac{\partial u}{\partial x_j} - h(\varphi_j(t^\mu, x^{m+i}) + \varphi_j(t^\mu, x^{m-i})) + 0(h^2), \end{aligned}$$

for $i \in I_2$:

$$\begin{aligned} 2(u^{\mu m+i+j} - u^{\mu m+i}) + h(\varphi_j(t^\mu, x^m) - \varphi_j(t^\mu, x^{m+i}) + \varphi_i(t^\mu, x^m)) - \\ - \varphi_i(t^\mu, x^{m+j}) = h^2 \frac{\partial^2 u}{\partial x_j^2} + 2 \frac{\partial^2 u}{\partial x_i \partial x_j} + h(\varphi_j(t^\mu, x^m) - \varphi_j(t^\mu, x^{m+i}) + \\ + \varphi_i(t^\mu, x^m) - \varphi_i(t^\mu, x^{m+j})) + 0(h^2), \end{aligned}$$

for $i \in I_3$:

$$2(u^{\mu\mu-i+j} - u^{\mu\mu-i}) + h(\psi_i(t^\mu, x^{m+i}) - \psi_i(t^\mu, x^m) + \varphi_j(t^\mu, x^m) - \varphi_j(t^\mu, x^{m-i})) = h^2 \frac{\partial^2 u}{\partial x_j^2} - 2 \frac{\partial^2 u}{\partial x_i \partial x_j} + h(\psi_i(t^\mu, x^{m+i}) - \psi_i(t^\mu, x^m) + \varphi_j(t^\mu, x^m) - \varphi_j(t^\mu, x^{m-i})) + O(h^2)$$

and finally

$$2(u^{\mu\mu+j} - u^{\mu\mu} - h\varphi_j(t^\mu, x^m)) = h^2 \frac{\partial^2 u}{\partial x_j^2} + O(h^2)$$

Replacing $\varphi_i, \varphi_j, \psi_i$ by suitable derivatives from (1.2) yields

$$\sigma u^{M_{ij}} = \frac{\partial^2 u}{\partial x_j^2} + O(1) \text{ as } h \rightarrow 0$$

that completes the proof of 1° if $m_j = 0$. A similar result can be obtained if we put $m_j = N$.

Now we shall prove 2°. Putting $m_i = N$ and using (2.8) we get for $1 \leq m_j \leq N-1$ the formula

$$\rho u^{M_{ij}} = \frac{1}{4h^2} (2h\psi_i(t^\mu, x^{m+i}) - 2h\psi_i(t^\mu, x^{m-j}))$$

Hence

$$\rho u^{M_{ij}} = \frac{\partial^2 u}{\partial x_i \partial x_j} + O(1) \text{ as } h \rightarrow 0$$

We can obtain similar results by putting $m_j = 0$ or $m_j = N$. When $m_i = 0$ the proof is similar.

This completes the proof of Lemma 1.

6. Denote

$$(6.1) \quad |n| = \sum_{s=1}^p |n_s|,$$

where n_s are integers and $n = (n_1, \dots, n_p)$.

Consider the difference equation with the unknown function $r^{\mu m}$

$$(6.2) \quad \frac{r^{\mu+1m} - r^{\mu m}}{k} = L^{\mu m} r^{\mu m} + \frac{1}{h} \left(P^0 r^{\mu m} + \sum_{0 < |n| \leq 2} P^n r^{\mu m + n} \right) + \eta^{\mu m}$$

and put

$$(6.3) \quad L = \max \{L^{\mu m} : \mu, m \in Z\}$$

$$(6.4) \quad \varepsilon^\mu = \max_{v \leq \mu} \max_m |\eta^{vm}| \quad (v, m) \in Z$$

The following Lemma is a particular case of Theorem 1 in paper [3]:

Lemma 2. If

$$P^n \geq 0 \text{ for } 0 < |n| \leq 2, \quad P^0 + \sum_{0 < |n| \leq 2} P^n = 0,$$

$$1 + kL^{\mu m} + \frac{k}{h} P^0 \geq 0$$

then the solution of (6.2) satisfies the inequality

$$|r^{\mu m}| \leq \frac{\varepsilon^\mu}{L} (e^{kL\mu} - 1)$$

in the set Z .

7. We are going to describe the approximate solution v^M . We put

$$(7.1) \quad \begin{aligned} v^{0m} &= \varphi(x^m), \quad \delta v^{Mj} = \varphi_j(t^\mu, x^m) \quad \text{for } m_j = 0, M \in Z, \\ \delta v^{Mj} &= \psi_j(t^\mu, x^m) \quad \text{for } m_j = N, M \in Z, \quad j = 1, \dots, p. \end{aligned}$$

For the nodal points $M \in Z$ we calculate the v^M successively from the equation

$$(7.2) \quad \frac{v^{\mu+1m} - v^{\mu m}}{k} = f(t^\mu, x^m, v^M, \delta v^M, \sigma v^M, \varrho v^M)$$

and for $M \in Z^+ \setminus Z$ the v^M are defined by the right hand sides of (4.1) with u replaced by v .

It is easily verified that the function v is well-defined for any nodal point M .

8. We denote

$$(8.1) \quad r^M = u^M - v^M$$

Now we are ready to prove the following

Theorem. If the assumptions A are fulfilled for the equation (1.1), the accurate solution u^M satisfies (4.1), (4.2), (5.1), the approximate solution v^M is defined by (7.1), (7.2) and (4.1), the error r^M is defined by (8.1) and the function ε^μ by (6.4), then

1° r^M satisfies the inequality (6.5),

2° the difference method (7.2) is convergent i.e. for each $T > 0$

$$\lim_{h \rightarrow 0} r^M = 0$$

uniformly in the set D_T .

Proof. Using the mean-value theorem we obtain as in [1]:

$$\begin{aligned} \frac{r^{\mu+1m} - r^{\mu m}}{k} &= \frac{\partial f}{\partial u} r^{\mu m} + \frac{1}{2h} \sum_i \left(\frac{\partial f}{\partial p_i} + \frac{2\beta}{h} \frac{\partial f}{\partial q_i} - \frac{4\alpha}{(p-1)h} \sum_{j \neq i} \frac{\partial f}{\partial q_j} \right) r^{\mu m+i} + \\ &+ \frac{1}{2h} \sum_i \left(-\frac{\partial f}{\partial p_i} + \frac{2\beta}{h} \frac{\partial f}{\partial q_i} - \frac{4\alpha}{(p-1)h} \sum_{j \neq i} \frac{\partial f}{\partial q_j} \right) r^{\mu m-i} + \end{aligned}$$

